

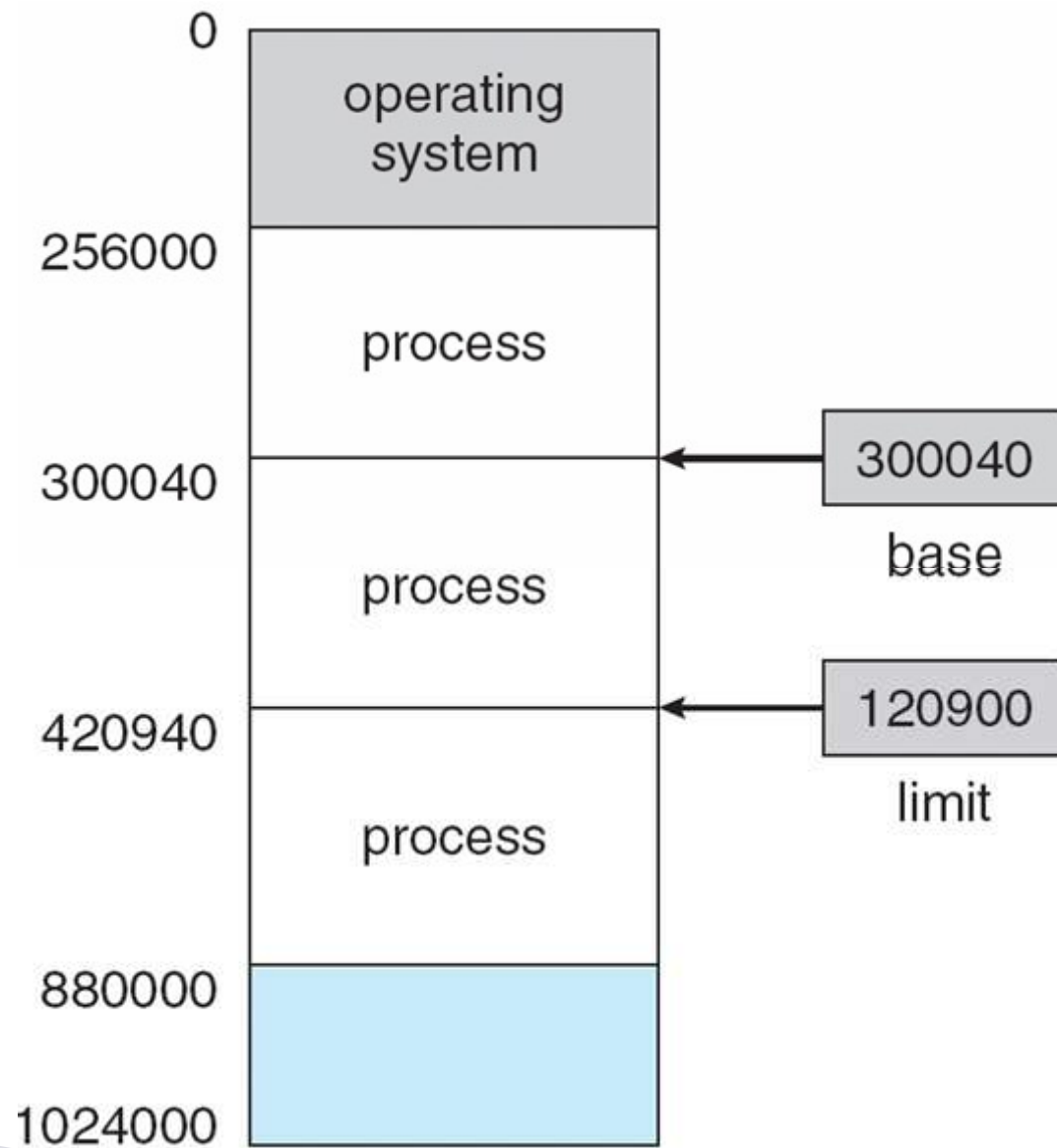
# Memory Management

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# Background

- ▶ Memory --- large array of words or bytes with its own address
- ▶ CPU fetches instructions from memory according to the value of program counter
- ▶ Instructions cause additional loading from and storing to specific memory address
- ▶ Fetches -- Decode -- Execute





# Address Binding

- ▶ The collection of processes on the disk that is waiting to be brought in to memory for execution forms the input queue.
- ▶ Select one from input queue and load to memory.
- ▶ Inconvenient to have first user process physical address always at 0000



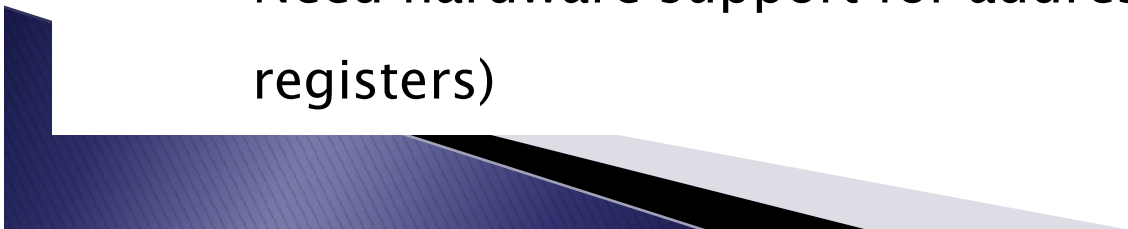
# Address Binding

- ▶ Further, addresses represented in different ways at different stages of a program's life
  - Source code addresses usually symbolic
  - Compiled code addresses **bind** to relocatable addresses
    - i.e. “14 bytes from beginning of this module”
  - Linker or loader will bind relocatable addresses to absolute addresses
    - i.e. 74014
  - Each **binding maps one address space to another**

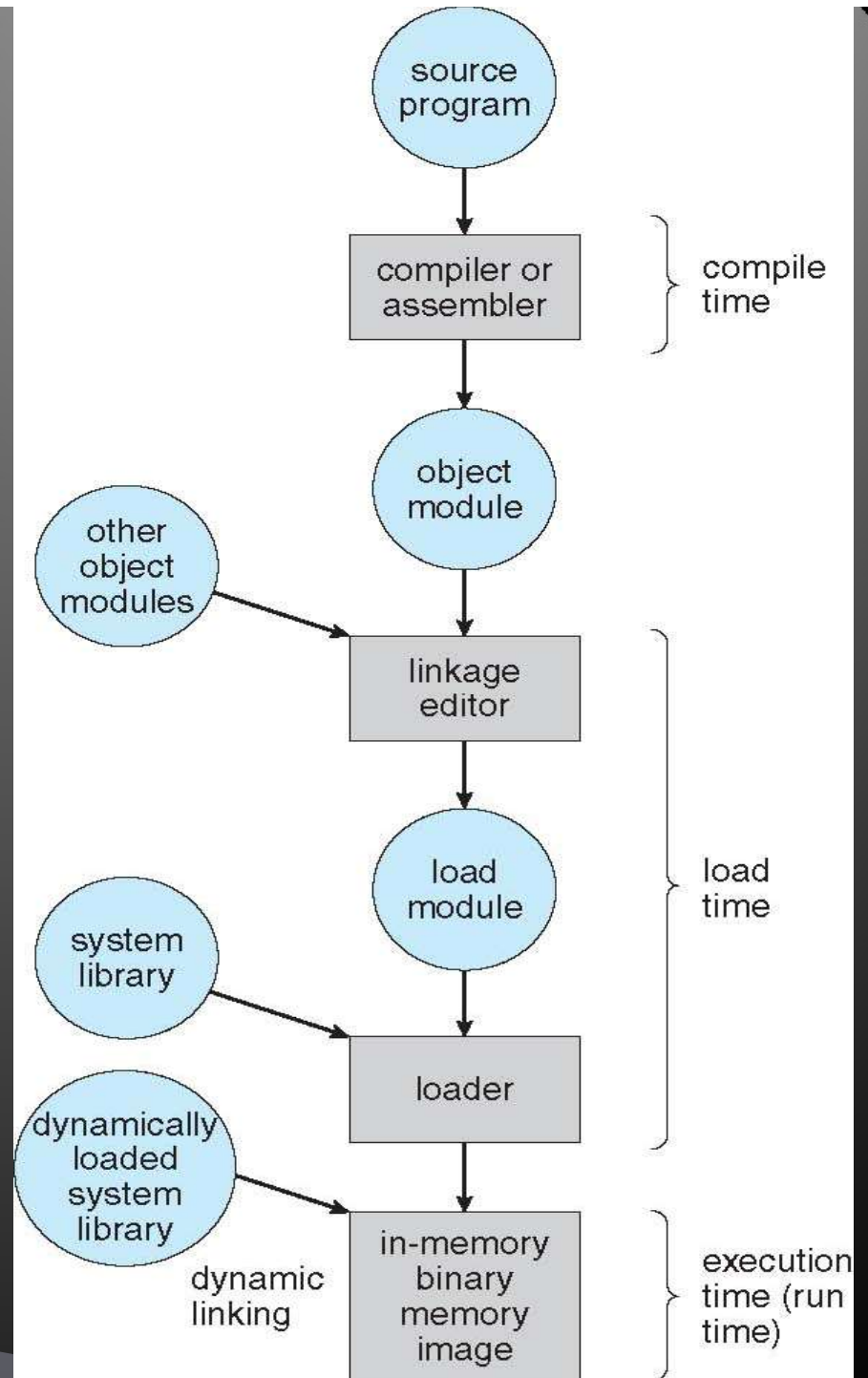


# Binding of Instructions and Data

- ▶ Address binding of instructions and data to memory addresses can happen at three different stages
  - **Compile time:** If memory location known a priori, **absolute code** can be generated; must recompile code if starting location changes (**early binding**)
  - **Load time:** Must generate **relocatable code** if memory location is not known at compile time (**delayed binding**)
  - **Execution time:** Binding delayed until run time if the process can be moved during its execution from one memory segment to another (**late binding**)
    - Need hardware support for address maps (e.g., base and limit registers)



# Multistep Processing of a User Program



# Logical vs. Physical Address Space

- ▶ The concept of a logical address space that is bound to a separate physical address space is central to proper memory management
  - **Logical address** – generated by the CPU; also referred to as virtual address
  - **Physical address** – address seen by the memory unit
- ▶ Logical and physical addresses are the same in compile-time and load-time address-binding schemes; logical (virtual) and physical addresses differ in execution-time address-binding scheme
- ▶ Logical address space is the set of all logical addresses generated by a program
- ▶ Physical address space is the set of all physical addresses generated by a program

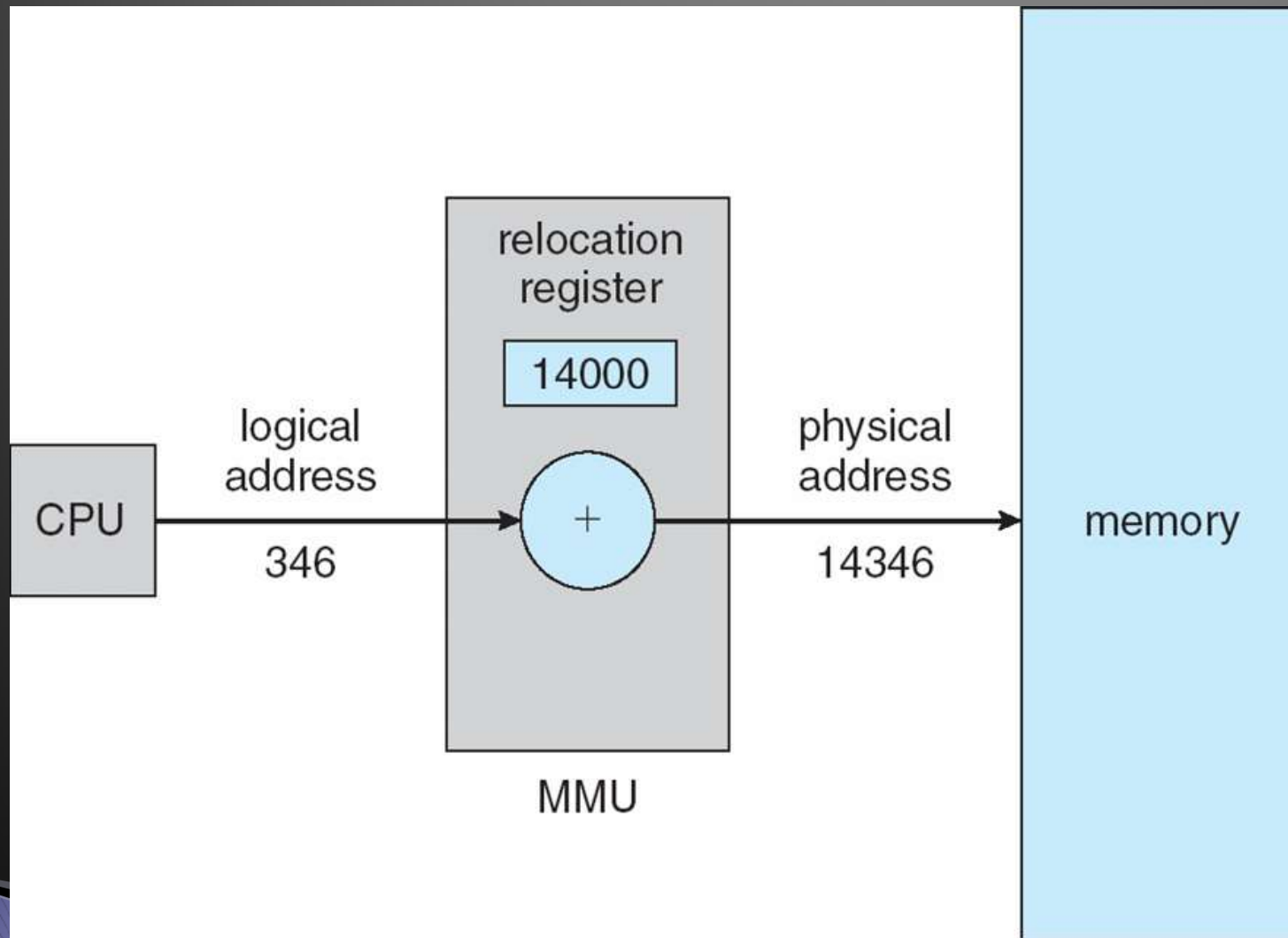




# Memory-Management Unit (MMU)

- ▶ Hardware device that at run time maps virtual to physical address
- ▶ To start, consider simple scheme where the value in the relocation register is added to every address generated by a user process at the time it is sent to memory
  - Base register now called **relocation register**
  - MS-DOS on Intel 80x86 used 4 relocation registers
- ▶ The user program deals with *logical* addresses; it never sees the *real* physical addresses
  - Execution-time binding occurs when reference is made to location in memory
  - Logical address bound to physical addresses

# Dynamic relocation using a relocation register



# Dynamic Loading

- ▶ Still we considered that entire program and data of a process must be in physical memory for the process of execute.
- ▶ The size of the process is limited to size of physical memory.
- ▶ For better utilization – Dynamic loading, ie a routine is not loaded until it is called.
- ▶ Unused routines are never loaded.
- ▶ It is the responsibility of the users to design their programs to take advantage of this method

# Dynamic Linking

- ▶ **Static linking** – system libraries and program code combined by the loader into the binary program image
- ▶ Dynamic linking – linking postponed until execution time
- ▶ Small piece of code, **stub**, used to locate the appropriate memory–resident library routine
- ▶ Stub replaces itself with the address of the routine, and executes the routine
- ▶ Operating system checks if routine is in processes' memory address
  - If not in address space, add to address space
- ▶ Dynamic linking is particularly useful for libraries
- ▶ System also known as **shared libraries**
- ▶ Consider applicability to patching system libraries
  - Versioning may be needed



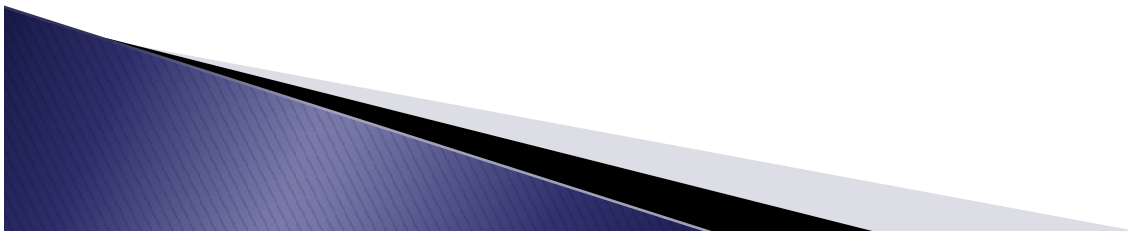
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- ▶ Consider applicability to patching system libraries
- ▶ Dynamic linking needs help from Operating system.



# Overlays

- ▶ To keep in memory only those instructions and data that are needed at any given time.
- ▶ Preparation of Mutually exclusive instruction and data set to be loaded.
- ▶ Need not require any support from OS



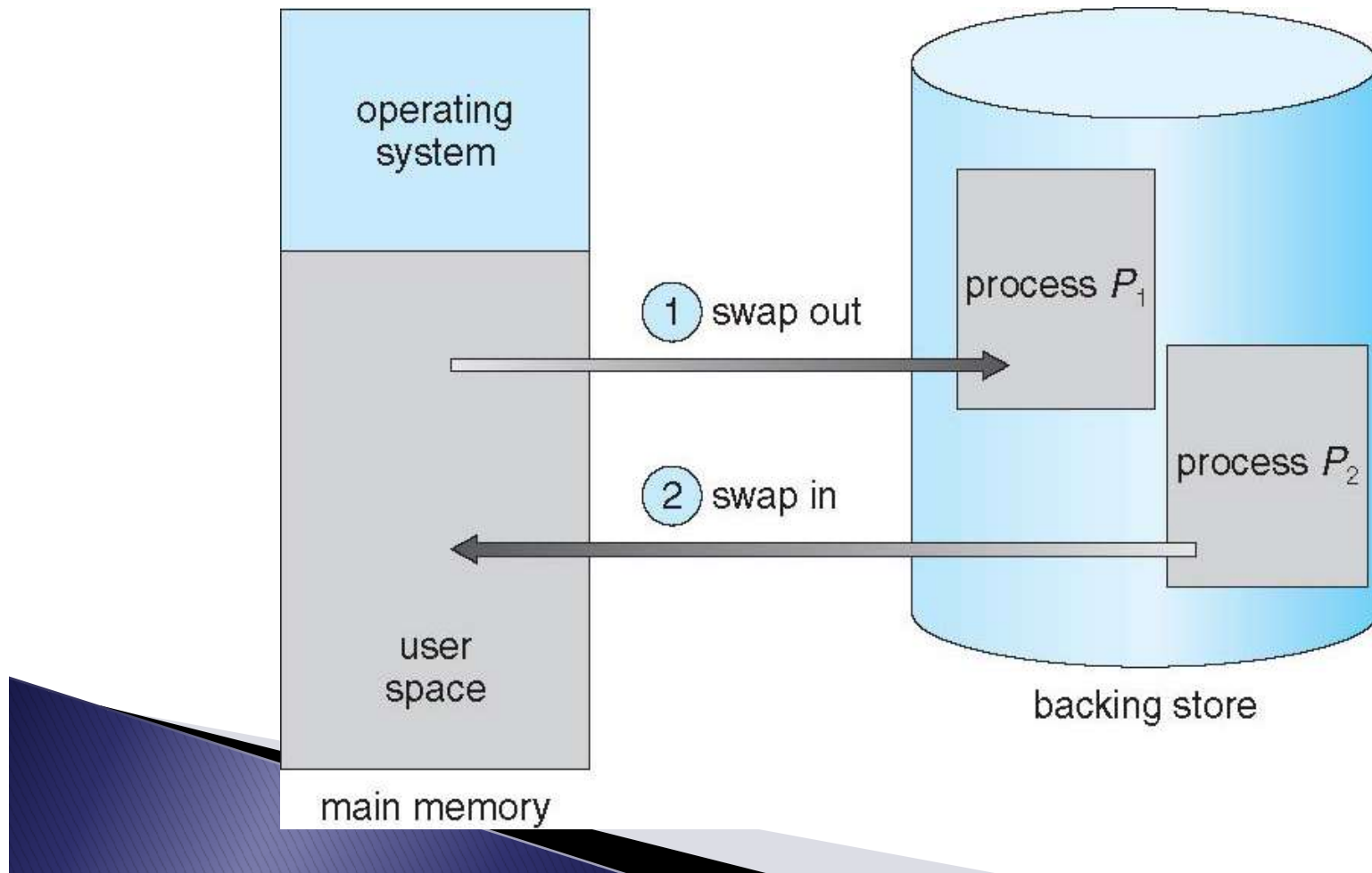
# Swapping

- ▶ A process can be **swapped** temporarily out of memory to a backing store, and then brought back into memory for continued execution
- ▶ **Backing store** – fast disk large enough to accommodate copies of all memory images for all users; must provide direct access to these memory images
- ▶ **Roll out, roll in** – swapping variant used for priority-based scheduling algorithms; lower-priority process is swapped out so higher-priority process can be loaded and executed
- ▶ Major part of swap time is transfer time; total transfer time is directly proportional to the amount of memory swapped
- ▶ System maintains a **ready queue** of ready-to-run processes which have memory images on disk



# Swapping (Cont.)

- ▶ Does the swapped out process need to swap back in to same physical addresses?
- ▶ Depends on address binding method
  - Plus consider pending I/O to / from process memory space





# Context Switch Time including Swapping

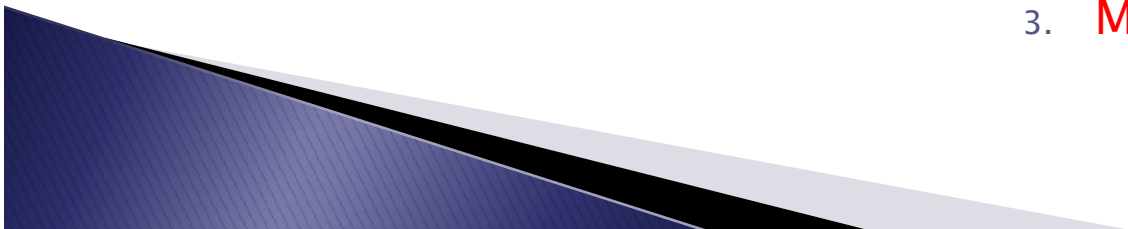
- ▶ If next processes to be put on CPU is not in memory, need to swap out a process and swap in target process
- ▶ Context switch time can then be very high
- ▶ 100MB process swapping to hard disk with transfer rate of 50MB/sec
  - Swap out time of 2000 ms
  - Plus swap in of same sized process
  - Total context switch swapping component time of 4000ms (4 seconds)



# Contiguous Allocation

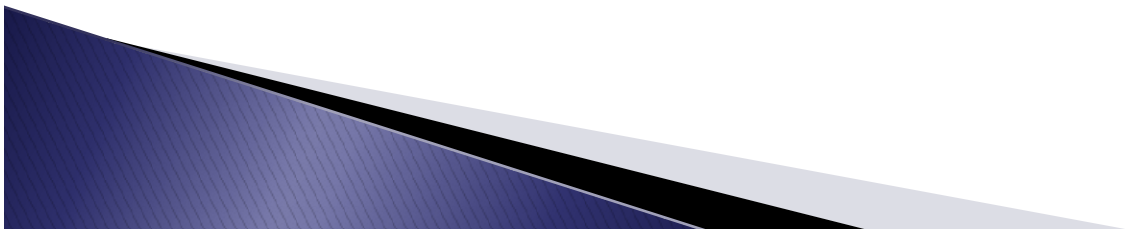
- ▶ Main memory must support both OS and user processes
- ▶ Limited resource, must allocate efficiently
- ▶ Contiguous allocation is one early method
- ▶ Main memory usually into two **partitions**:
  - Resident operating system, usually held in low memory with interrupt vector
  - User processes then held in high memory
  - Each process contained in single contiguous section of memory

1. **Single Contiguous**
2. **Multiple Fixed Partitioned**
3. **Multiple Variable partitioned**

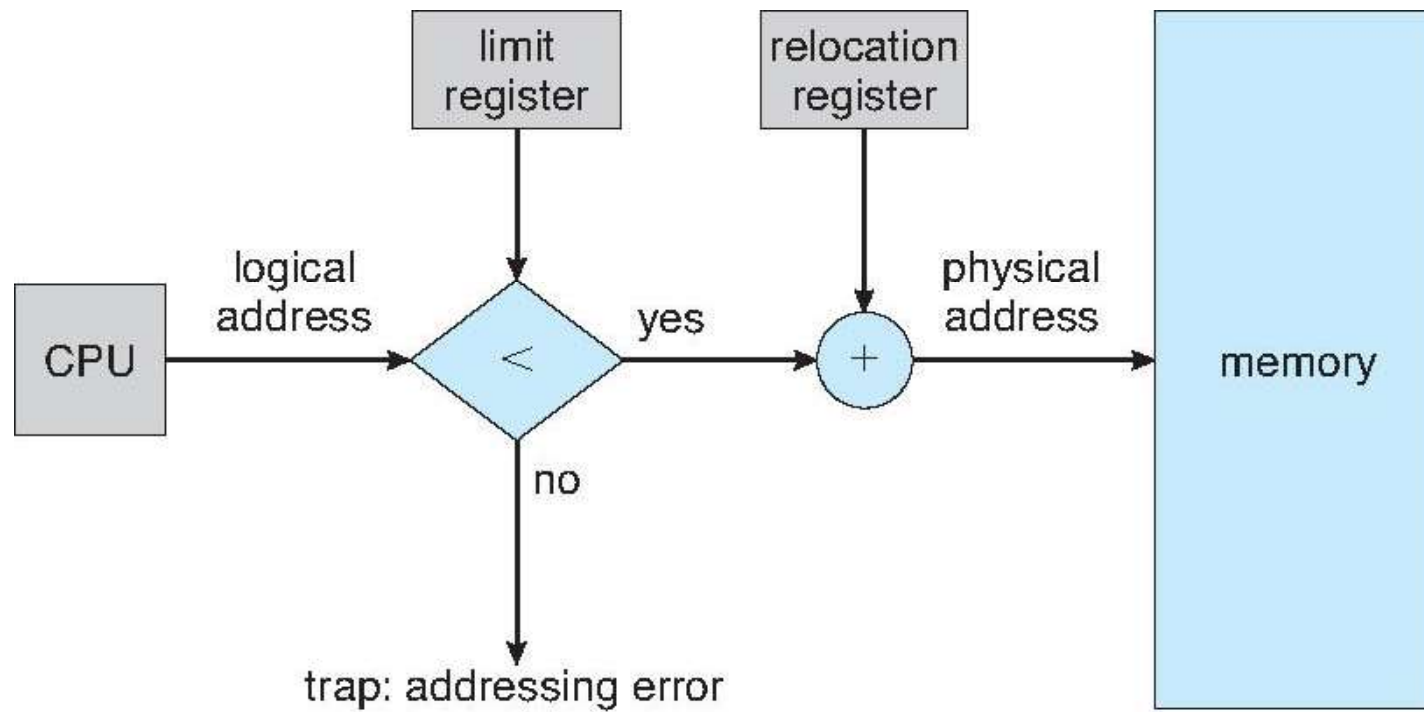


# Contiguous Allocation (Cont.)

- ▶ Relocation registers used to protect user processes from each other, and from changing operating-system code and data
  - Base register contains value of smallest physical address
  - Limit register contains range of logical addresses – each logical address must be less than the limit register
  - MMU maps logical address *dynamically*

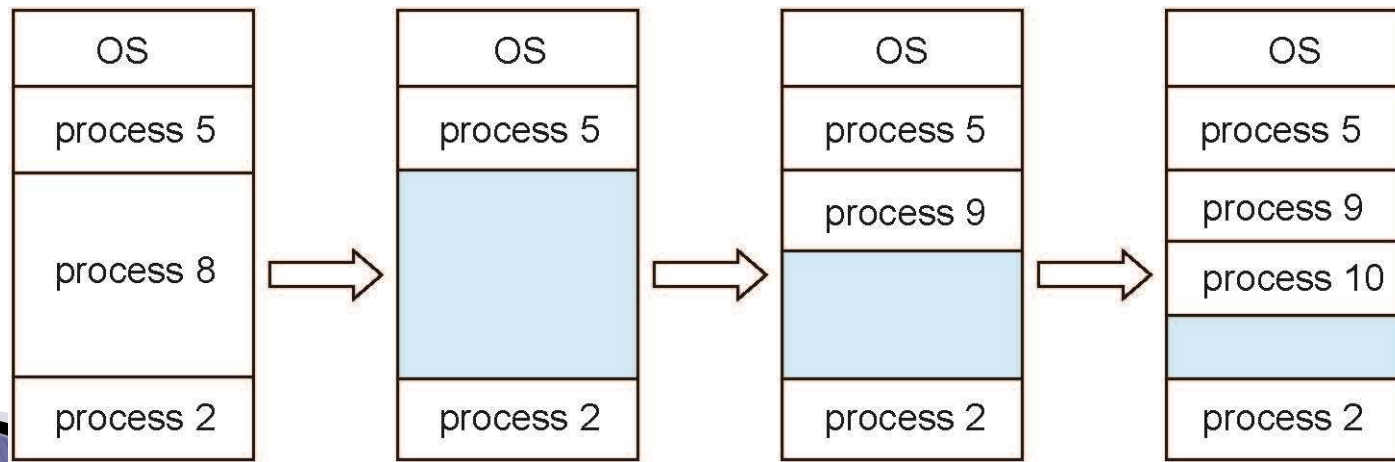


# Hardware Support for Relocation and Limit Registers



# Multiple-partition allocation

- ▶ Multiple-partition allocation
  - Degree of multiprogramming limited by number of partitions
  - **Variable-partition** sizes for efficiency (sized to a given process' needs)
  - **Hole** – block of available memory; holes of various size are scattered throughout memory
  - When a process arrives, it is allocated memory from a hole large enough to accommodate it
  - Process exiting frees its partition, adjacent free partitions combined
  - Operating system maintains information about:
    - a) allocated partitions
    - b) free partitions (hole)

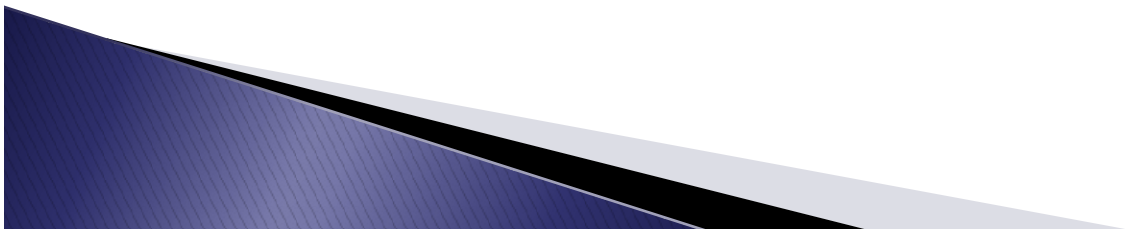


# Dynamic Storage–Allocation Problem

How to satisfy a request of size  $n$  from a list of free holes?

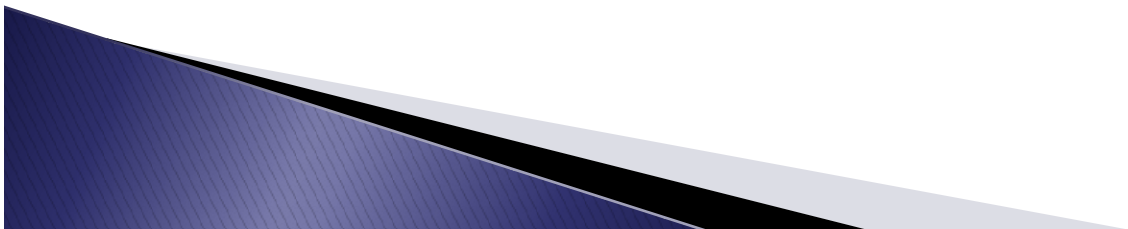
- ▶ **First–fit**: Allocate the *first* hole that is big enough
- ▶ **Best–fit**: Allocate the *smallest* hole that is big enough; must search entire list, unless ordered by size
  - Produces the smallest leftover hole
- ▶ **Worst–fit**: Allocate the *largest* hole; must also search entire list
  - Produces the largest leftover hole

First-fit and best-fit better than worst-fit in terms of speed and storage utilization



# Fragmentation

- ▶ **External Fragmentation** – total memory space exists to satisfy a request, but it is not contiguous
- ▶ **Internal Fragmentation** – allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used
- ▶ First fit analysis reveals that given  $N$  blocks allocated,  $0.5 N$  blocks lost to fragmentation
  - $1/3$  may be unusable → **50-percent rule**



# Fragmentation (Cont.)

- ▶ Reduce external fragmentation by **compaction**
  - Shuffle memory contents to place all free memory together in one large block
  - Compaction is possible *only* if relocation is dynamic, and is done at execution time
  - I/O problem
    - Latch job in memory while it is involved in I/O
    - Do I/O only into OS buffers

